A Novel Approach to the Simulation of Particles on a Large Size-Range

Alexander Schinner

Otto-von-Guericke Universität Magdeburg, Germany

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MD-Simulation of granular materials

 $\downarrow \downarrow$

slowly changing system

 $\downarrow \downarrow$

The last time-step's information is nearly correct.

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Reuse this information as good starting conditions.

The steps of our MD-simulation

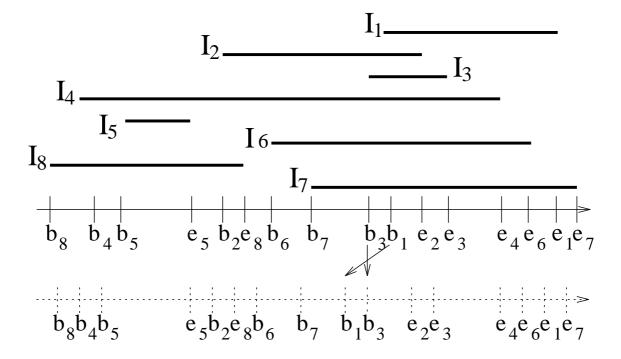
- 1. Check for bounding box collisions
- 2. Check for particle collisions
- 3. Calculate overlap
- 4. Do the physics (not discussed here)

Increasing need of time

Try to exclude as many particle-pairs as possible from being considered in the next level.

Bounding Boxes

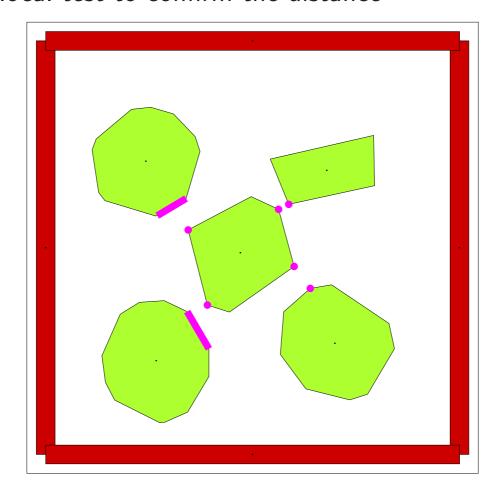
First consider the one dimensional case:



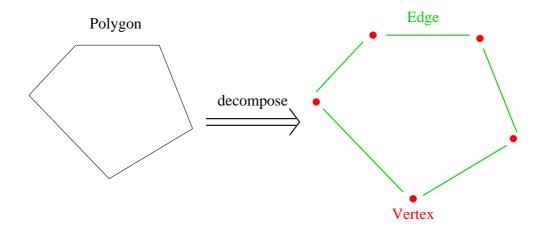
- \bullet Resorting the List of Boundingbox boundaries is possible with $\mathcal{O}(N)$ steps, if we use Insertion Sort
- During the sorting we can update the list of all collisions
- \Rightarrow Total cost of $\mathcal{O}(N)$.

Closest Feature Algorithm

- Calculate distance of particles
- keep track of the closest features
- local test to confirm the distance



Feature



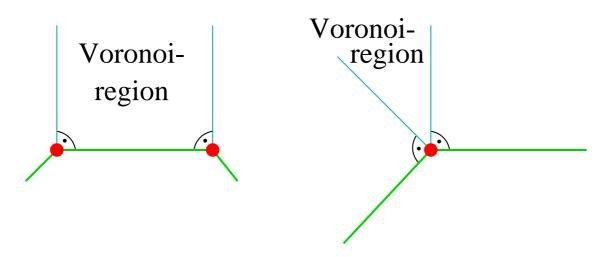
A feature has information on its

- type (edge or vertex)
- geometry
- neighbors
- Voronoi regions
- and more...

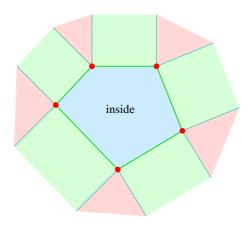
Voronoi Region

If a point p lies inside the Voronoi region of a feature f_a , then

$$\operatorname{dist}(p, f_a) \leq \operatorname{dist}(p, f_b)$$

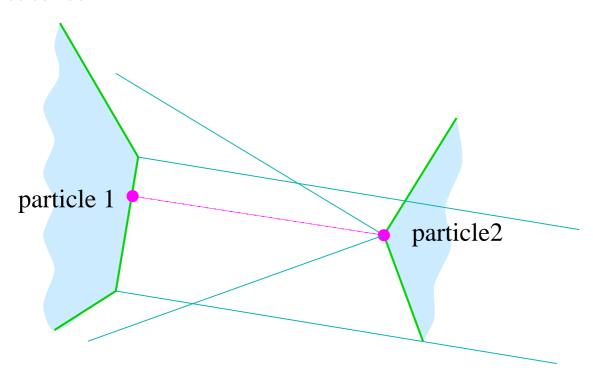


This divides the space outside a particle:



Closest features

If a point P on object P_1 lies inside the Voronoi region of f_2 on object P_2 , then f_2 is a closest feature to the point P and vice versa for an Voronoi region of f_1 . If we have a pair of features fulfilling the above condition, we have a pair of closest features.



Closest Feature Algorithm

We are looking on two features f_1 and f_b on two polyhedra P_1 and P_2 .

- 1. Calculate the Voronoi regions V_1 and V_2
- 2. Calculate a point p_1 on f_1 that is the closest to f_2 and a point p_2 on f_2 that is the closest to f_a
- 3. Check for $p_1 \in V_2$. If not: choose new f_1 and restart algorithm
- 4. Check for $p_2 \in V_1$. If not: choose new f_2 and restart algorithm